

# Ramón Calvo González

<https://noctrog.github.io>

Email : r.calvo@ieee.org

Mobile : +34-633 72 71 78

## EDUCATION

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- **University of Alicante**

*Bachelor of Robotics Engineering — (Current grade: 9.15/10)*

Alicante, Spain

Sep. 2017 – Present

## EXPERIENCE

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- **QuixMind**

*Internship*

Alicante, Spain

July 2019 – Present

- **ROS Robot Simulation:** modeled a robot forklift and its environment, simulated using Gazebo.
- **Sensors:** took measurements from perception sensors (LIDAR, Intel RealSense) and processed them in order to perform control tasks.
- **Communications:** connected the ROS application to a Windows app through TCP/IP, using compression to accelerate the transmission rate.
- **Docker:** containerized ROS environment so it can be run anywhere.

## COURSES AND TRAINING

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- **Udacity**

*Intro to Deep Learning with Pytorch*

July 2019

- **Coursera**

*Machine Learning*

June 2019

- **University of Alicante**

*CUDA/C++ Workshop*

March 2019 – April 2019

## SKILLS

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- **Languages:** C, C++, Python, MATLAB/Octave, Rust
- **Tools:** ROS, Modern OpenGL, SDL, PyTorch, L<sup>A</sup>T<sub>E</sub>X
- **Linux:** Bash, GDB, GNU Make, Vim, Tmux, Git, SSH, basic sysadmin skills
- **CAD:** KiCAD, Autodesk Inventor, Autodesk FUSION 360
- **Embedded Systems:** AVR, STM32, FreeRTOS, libopencm3
- **Machine Learning:** Deep Learning, Reinforcement Learning
- **Other :** 3D printing, soldering

## LANGUAGES

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- **Spanish:** Native

- **English:** Fluent (B2)

## PROJECTS

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- **Image Captioning:** implementation in Pytorch of the paper CNN+CNN: Convolutional decoders for Image Captioning
- **DDQN:** implementation of Double Dueling DQN in Pytorch, trained in Breakout OpenAI environment
- **3D Cellular Automata:** A 3D version of Game of Life using C++ & OpenGL.
- **Bluetooth-controlled 3-stage coil gun tank:** powered by an AVR MCU and controlled through an Android App.
- **Scientific Calculator:** designed from scratch, powered by an ARM Cortex M0 MCU using MBED.

## CONFERENCES

## MISCELLANEOUS

- **GitHub:** <https://github.com/noctrog>
- **LinkedIn:** Link