





RESEARCH INTERESTS

My research interests lie where data-driven control methods, machine perception and large scale models converge, enabling autonomous systems to build a rich world model that helps them comprehend their surroundings and reason about their actions.











SKILLS

Python | C | C++ | Git | GDB | MATLAB | CMake | PyTorch | CUDA | Isaac | Warp | OpenGL | OpenCV | Linux | Deep Learning | Reinforcement Learning | Machine Perception | Docker | ROS | Gazebo | Point Cloud Library | OpenGL | Sysadmin | \LaTeX | Rust | Julia | Blender | Embedded Systems | Spanish (native) | English (bilingual) | Catalan (proficient)

EDUCATION

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| MSc Robotics, Systems and Control | <u>ETH Zürich</u> |  Zürich, CH  9/2021 – Present |
| ◦ ESOP Scholar: Merit based scholarship and mentorship given to the top 3% of ETH MSc applicants of 2021. | | |
| BEng Robotics Engineering | <u>University of Alicante</u> |  Alicante, ES  9/2017 – 6/2021 |
| ◦ Extraordinary award: graduated best-in-class (1st out of 271 students). | | |

EXPERIENCE

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| Master Thesis | <u>Robotics Systems Lab</u> |  Zürich, CH  4/2023 – Present |
| ◦ Creating end-to-end safe navigation reinforcement learning policies for wheeled-legged robots that leverage perceived terrain semantics, using PyTorch, IsaacGym and Warp. | | |
| ◦ Made a framework for creating realistic procedural terrains with hiking trails, using Blender and its Python API. | | |
| ◦ Supervised by Joonho Lee and Marko Bjelonic. | | |
| Research Engineer Intern | <u>SONY R&D Center</u> |  Zürich, CH  9/2022 – 2/2023 |
| ◦ Researched on small Deep Learning models for object detection with event cameras on embedded hardware. | | |
| ◦ Implemented a CNN-RNN baseline architecture using Pytorch, Lightning and Hydra. | | |
| ◦ Implemented a state-of-the-art Vision Transformer (ViT) model that outperformed the baseline's IoU by 50% while having 5x less parameters. | | |
| ◦ Created a large dataset pipeline: speed-up of 100x while handling 1TB of data. | | |
| Research Assistant | <u>Computational Robotics Lab</u> |  Zürich, CH  7/2022 – 8/2022 |
| ◦ Researched the use of learned actuator dynamics using neural networks in a Whole Body Controller (WBC). | | |
| ◦ Supervised by Dongho Kang, Joonho Lee and Prof. Stelian Coros. | | |
| Research Intern | <u>Human Robotics</u> |  Alicante, ES  10/2020 – 6/2021 |
| ◦ Research funded by the merit based Collaboration Grant issued by the Spanish Ministry of Education. | | |
| ◦ Bipedal gait generation and tracking through trajectory optimization and a custom made WBC, using C++ and ROS. | | |
| ◦ Supervised by Prof. Jorge Pomares. | | |
| Engineering Intern | <u>QuixMind</u> |  Alicante, ES  10/2019 – 6/2020 |
| ◦ Created a robot forklift simulation with ROS, Gazebo and Docker. | | |
| ◦ Pallet pose estimation and alignment on a real forklift, using the Point Cloud Library, ROS Controllers and C++. | | |

PUBLICATIONS

- Path generation and control of humanoid robots during extravehicular activities.
Ramón JL, **Calvo R**, Trujillo A, Pomares J, Felicetti L. 73rd International Astronautical Congress (IAC-22), 18-22 September 2022, Paris, France
- Trajectory optimization and control of a free-floating two arms humanoid.
Ramón JL, **Calvo R**, Trujillo A, Pomares J, Felicetti L. Journal of Guidance, Control and Dynamics 45 (9), 1661-1675. 2022

REFERENCES

- Stelian Coros | Associate Professor at ETH Zürich | ✉ scoros@inf.ethz.ch
- Jorge Pomares Baeza | Full Professor at the University of Alicante | ✉ jpomares@ua.es
- Valentina Cavinato, Senior Engineer at SONY Europe B.V. | 📞 +41 (0) 79 766 38 99 | ✉ valentina.cavinato@sony.com

AWARDS

Ideathon For a Novel Sustainable Packaging Material <i>First prize (Proposed a method to obtain PHA candidates using ML and produce them at scale)</i>	Student Biolab – ETH Zurich November 2022
ESOP (Excelence Scholarship & Opportunity Program) <i>Merit based scholarship and mentorship awarded to the top 3% MSc applicants of 2021 at ETH Zürich.</i>	ETH Zurich March 2021
Extraordinary Bachelor's Award <i>Graduated with Honors</i>	University of Alicante November 2021
National Graduate Ranking <i>2nd position in my engineering category</i>	SEDEA (Spain) November 2021
Santander's Progreso Grant <i>Awarded for being one of the best students in campus.</i>	Santander Bank December 2020
Ministry Collaboration Grant <i>Research internship in University of Alicante's DFESTS department.</i>	Spanish Ministry of Education 2020 – 2021

VOLUNTEERING

- Volunteer at ICIAM 2019.
- Volunteer at IROS 2018 (IEEE stand).